

Generalized Linear Models

Lecture 8: Hierarchical models and longitudinal data





2 Hierarchical Linear Models (HLM)

3 Longitudinal data

- Handle data where observations are not independent.
- Uncorrelated error is important but often violated.
- Violations occur when error terms are not independent but instead cluster by one or more grouping variables.
 - For instance, predicted student test scores and errors in predicting them may cluster by classroom, school, and municipality.
- LMM can lead to substantially different conclusions compared to conventional regression analysis.

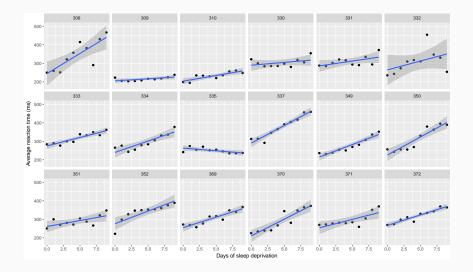
Linear mixed models are a generalization of general linear models to better support analysis of a continuous dependent variable for *random effects*.

Bear in mind:

Fixed effects: variables that we expect will have an effect on the dependent/response variable.

Random effects: grouping factors and they are categorical. Often we are not specifically interested in their impact on the response variable. Additionally, the data for our random effect is just a sample of all the possibilities.

A revisit to sleepstudy data



Why not include dummy variables?

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Benefits of using random effects

- We can generalize to a wider population.
- 2 Fewer parameters are needed.
- ³ Information can be shared between groups.

- 1 *Hierarchical effects:* When variables are measured at more than one level. Assess the effects of higher levels on the intercepts and coefficients at the lowest level.
 - scores at student level and teacher-student ratios at school level
 - sentencing lengths at the offender level, gender of judges at the court level, and budgets of judicial districts at the district level
- 2 *Repeated measures:* For when observations are correlated rather than independent. e.g., before–after studies, time series data.

1 Linear Mixed Models (LMM)

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Levels of one factor vary only within levels of another factor.

- Workers within job locations
- Units within campus

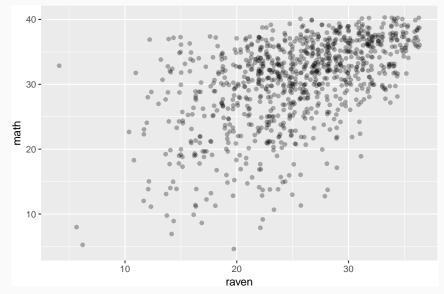
- Any non-nested effects are "crossed".
- That is, every level of one factor can potentially interact with every level of another factor.
- Incomplete crossing occurs when not all combinations of factors exist in the data.

- Models with nested (hierarchical) structure.
- Commonly used in psychology, education, and other social sciences where survey data is naturally clustered hierarchically.

Junior School Project (1988)

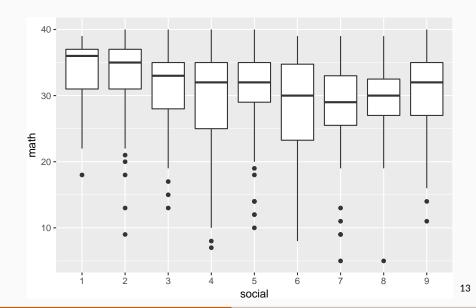
Variables: student, class, school, gender, social, raven, math, english, year Nesting: school:class:student Other variables crossed.

Plot our data - faraway :: jsp



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Plot our data



```
glin <- lm(math ~ raven*gender*social,jspr)
anova(glin)
glin <- lm(math ~ raven*social,jspr)
anova(glin)
glin <- lm(math ~ raven+social,jspr)
summary(glin)</pre>
```

All 953 students are independent?

2 Remember that they come from 50 different schools.

table(jspr\$school)

##																			
##	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
##	26	11	14	24	26	18	11	27	21	0	11	23	22	13	7	16	6	18	14
##	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	44	45
##	20	22	15	13	27	35	23	44	27	16	28	17	12	14	10	10	41	5	11

We need an analysis that uses the individual-level information, but also reflects the grouping in the data.

```
mmod <-
lmer(math ~ raven * social * gender +
(1 | school) +
(1 | school:class), data = jspr)</pre>
```

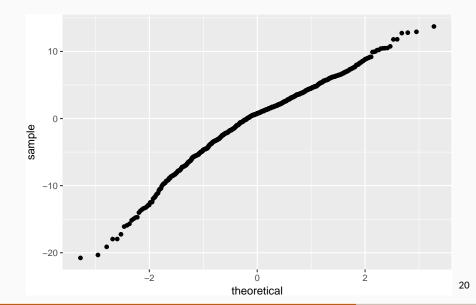
Model selection

all3 <- lmer(math ~ raven * social * gender + (1 | school) + (1 | school:class), data = jspr, REML = FALSE) all2 <- update(all3, . ~ . - raven:social:gender)</pre> notrs <- update(all2, . ~ . -raven:social)</pre> notrg <- update(all2, . ~ . -raven:gender)</pre> notsg <- update(all2, . ~ . -social:gender)</pre> onlyrs <- update(all2, . ~ . social:gender-raven:gender) all1 <- update(all2, . ~ . -social:gender raven:gender - social:raven) nogen <- update(all1, . ~ . -gender)</pre>

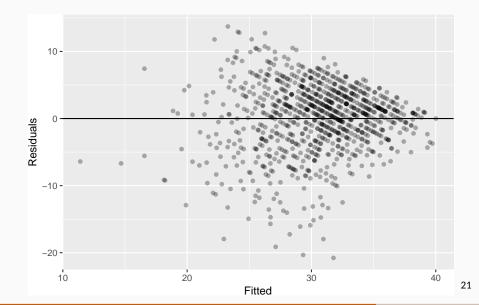
anova(all3, all2, notrs, notrg, notsg, onlyrs, all1, nogen)

##		Df	AIC	BIC	logLik
##	nogen	13	5954.3	6017.5	-2964.2
##	all1	14	5955.6	6023.6	-2963.8
##	onlyrs	22	5950.1	6057.0	-2953.1
##	notrs	23	5961.6	6073.4	-2957.8
##	notsg	23	5952.0	6063.8	-2953.0
##	notrg	30	5956.1	6101.9	-2948.1
##	all2	31	5957.8	6108.4	-2947.9
##	all3	39	5966.7	6156.2	-2944.3

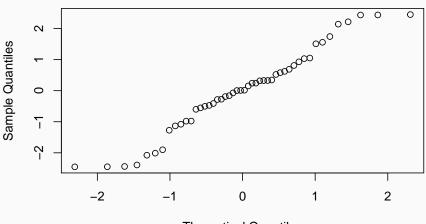
Model diagnosis: fixed effects



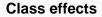
Model diagnosis: fixed effects

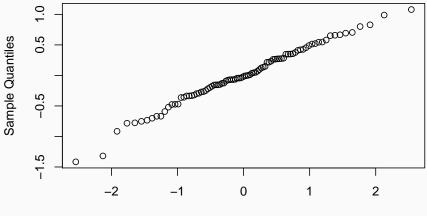






Theoretical Quantiles





Theoretical Quantiles



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- Repeated measurements on each unit taken over time.
- Called "panel data" in econometrics. Called "longitudinal data" in every other discipline.
- Individuals treated as random effects
- Differs from time series in having many units (e.g., people) but often not many observations per person.
- i.e., Longitudinal data has large N, small T; Time series data has small N, large T.

For unit (individual) i, y_i is a T-vector such that

 $\mathbf{y}_i | \gamma_i \sim N(\mathbf{X}_i \boldsymbol{eta} + \gamma_i, \sigma^2 \boldsymbol{\Lambda}_i)$

• $\gamma_i \sim N(0, \sigma^2 D)$ is effect of *i*th unit

- X_i contains predictors for fixed effects
- Λ_i handles autocorrelations within units
- **y**_i ~ $N(X_i\beta, \Sigma_i)$ where $\Sigma_i = \sigma^2(\Lambda_i + D)$

 Assume individuals are independent, and random effects and errors are uncorrelated. Combining individuals (assuming independence):

$$\mathbf{y} = \begin{bmatrix} \mathbf{y}_1 \\ \vdots \\ \mathbf{y}_N \end{bmatrix} \qquad \mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \vdots \\ \mathbf{X}_N \end{bmatrix}$$
$$\mathbf{\Sigma} = \operatorname{diag}(\mathbf{\Sigma}_1, \mathbf{\Sigma}_2, \dots, \mathbf{\Sigma}_N),$$
$$\mathbf{y} \sim N(\mathbf{X}\boldsymbol{\beta}, \mathbf{\Sigma})$$

Combining individuals (assuming independence):

$$\mathbf{y} = \begin{bmatrix} \mathbf{y}_1 \\ \vdots \\ \mathbf{y}_N \end{bmatrix} \qquad \mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \vdots \\ \mathbf{X}_N \end{bmatrix}$$
$$\Sigma = \operatorname{diag}(\Sigma_1, \Sigma_2, \dots, \Sigma_N),$$
$$\mathbf{y} \sim N(\mathbf{X}\beta, \Sigma)$$

Only additional complication is choosing correlation structure

• Other random effects can be added; then γ_i becomes a vector.